Quantum Mechanics & Quantum Computation

Umesh V. Vazirani University of California, Berkeley

Lecture 5: Quantum Gates

Time evolution of a quantum system

Axioms of quantum mechanics

Axiom 1. Superposition principle

Axiom 2. Measurement

Axiom 3. Unitary evolution

Superposition

• Allowable states of k-level system: unit vector in a k-dimensional complex vector space (called a Hilbert space).



Measurement

- A measurement is specified by choosing an orthonormal basis.
- The probability of each outcome is the square of the length of the projection onto the corresponding basis vector.
- The state collapses to the observed basis vector.



New State |4'> = |u;> (|(μ_i>, |ψ>)|² |Ψ) = α, 10) + · · · · + α_{κ-1} | κ-i> 14j) = Bolos + - · · · + BK+ 1K+1> (14;), 14) = Bodo + --- + Bu-10K-1 = ($\vec{P}_0 \ \vec{P}_1 \ \cdots \ \vec{P}_{k-1})$ Bra-Ket motation 1000 $\langle u_{j}| = (\overline{\beta}, \overline{\beta}, \cdots, \overline{\beta}_{\kappa_{1}})$ inner product = $< U_j | \psi >$ $P_{r}[_{i}] = |\langle u_{i}|\psi\rangle|^{2}$

Evolution

• How does the state evolve in time?

$$|\psi\rangle = \alpha_0|0\rangle + \dots + \alpha_{k-1}|k-1\rangle = \begin{pmatrix} \alpha_0 \\ \vdots \\ \alpha_{k-1} \end{pmatrix} \in \mathbb{C}^k$$

Evolution

• How does the state evolve in time? By a rotation of the Hilbert space!

$$|\psi\rangle = \alpha_0|0\rangle + \dots + \alpha_{k-1}|k-1\rangle = \begin{pmatrix} \alpha_0 \\ \vdots \\ \alpha_{k-1} \end{pmatrix} \in \mathbb{C}^k$$

Example: evolution of a qubit.



It is a rigid body rotation, meaning that the angles between vectors are preserved.

Rotation Matrix

- Rotation of the space is a linear transformation. Represent by a matrix:
- Example ٠ $R_{\theta}|\psi\rangle$ $R_{\theta}|0\rangle$ $R_{\theta}|1\rangle$ $R_{\theta} = \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix} \begin{bmatrix} -\sin \theta \\ \cos \theta \end{bmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix} \\ \begin{bmatrix} \sin \theta \\ \sin \theta \end{pmatrix} = \begin{bmatrix} \cos \theta \\ \sin \theta \\ -\sin \theta \end{bmatrix} = R_{\theta}^{T}$ $R_{\theta} R_{\theta}^{T} = R_{\theta}^{T} R_{\theta} = I$ unitary.

Rotation Matrix

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• Rotation of the space is a linear transformation. Represent by a matrix:

Example

$$|0\rangle \rightarrow cq\theta |0\rangle + sin\theta |1\rangle$$

$$|1\rangle \rightarrow -sin\theta |0\rangle + cq\theta |1\rangle$$

$$|1\rangle \rightarrow -sin\theta |0\rangle + cq\theta |1\rangle$$

$$|1\rangle \rightarrow -sin\theta |0\rangle + cq\theta |1\rangle$$

$$|0\rangle = (cq\theta |0\rangle + sin\theta |1\rangle)$$

$$|0\rangle = (cq\theta |0\rangle + sin\theta |1\rangle)$$

$$|0\rangle = (cq\theta |0\rangle + sin\theta |1\rangle)$$

$$+ \beta (-sin\theta |0\rangle + cq\theta |1\rangle)$$

$$+ \beta (-sin\theta |0\rangle + cq\theta |1\rangle)$$

$$R_{\theta} = (cq\theta - sin\theta) (0) = (\xi - (zq\theta - \beta sin\theta) |0\rangle + (\alpha sn\theta + \beta cq\theta) |1\rangle$$

$$R_{-\theta} = (cq\theta - sin\theta) = R_{\theta}^{T} \qquad R_{\theta} R_{-\theta} = I$$

$$R_{\theta} R_{\theta}^{T} = R_{\theta}^{T} R^{\theta} = I$$

Rotation Matrix

• Rotation of the space is a linear transformation. Represent by a matrix:

• Example

$$|0\rangle \rightarrow cq_{\theta}\theta |0\rangle + sin\theta |1\rangle$$

$$|1\rangle \rightarrow -sin\theta |0\rangle + cq_{\theta}\theta |1\rangle$$

$$|1\rangle \rightarrow -sin\theta |1\rangle$$

Unitary Transformations



 $\mathcal{U} = \begin{pmatrix} a & c \\ b & d \end{pmatrix} \qquad \mathcal{U}^{+} = \begin{pmatrix} \overline{a} & \overline{b} \\ \overline{c} & \overline{d} \end{pmatrix}$ $\begin{pmatrix} \overline{a} & \overline{b} \\ \overline{c} & \overline{d} \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} \begin{pmatrix} c \\ d \end{pmatrix} = I = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$ $\mathcal{U}|_{O} = \begin{pmatrix} a & c \\ b & d \end{pmatrix} \begin{pmatrix} i \\ o \end{pmatrix} = \begin{pmatrix} a \\ b \end{pmatrix} = \frac{a | o \rangle}{b} + \frac{b | i \rangle}{b}$ $U(1) = \begin{pmatrix} a & c \\ b & d \end{pmatrix} \begin{pmatrix} o \\ i \end{pmatrix} = \begin{pmatrix} c \\ d \end{pmatrix} = \frac{c(o) + d(i)}{c(d)}$ 10> 2 14> $\langle \phi | \psi \rangle$ $\underline{u}|\underline{w}\rangle < \phi|\underline{u}^{\dagger}\underline{u}|\underline{w}\rangle$ U/\$ 8







wire a qubit

"Bit flip"

$$\begin{aligned} \alpha_{0}|0\rangle + \alpha_{1}|1\rangle &\longrightarrow X &\longrightarrow \alpha_{1}|0\rangle + \alpha_{0}|1\rangle \\ X &= \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} & X |o\rangle = \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix} \begin{pmatrix} i \\ o \end{pmatrix} = \begin{pmatrix} 0 \\ i \end{pmatrix} = |i\rangle \\ X (i) = \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix} \begin{pmatrix} 0 \\ i \end{pmatrix} = \langle 0 \end{pmatrix} = |i\rangle \\ X^{\dagger}X = XX^{\dagger} = T = X^{2} \end{aligned}$$

"Phase flip"

$$\begin{array}{c} \alpha_{0}|0\rangle + \alpha_{1}|1\rangle \longrightarrow \boxed{Z} \longrightarrow \alpha_{0}|0\rangle - \alpha_{1}|1\rangle \\ Z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \qquad \boxed{Z}|0\rangle = \begin{pmatrix} i & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix} \end{pmatrix} \begin{pmatrix} i & 0 \\ 0 & 0 \end{pmatrix}$$

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"Hadamard transform"









$$H|0\rangle = |+\rangle = \frac{1}{\sqrt{2}}|0\rangle + \frac{1}{\sqrt{2}}|1\rangle$$
$$H|1\rangle = |-\rangle = \frac{1}{\sqrt{2}}|0\rangle - \frac{1}{\sqrt{2}}|1\rangle$$

"Bit flip" $\alpha_{0}|0\rangle + \alpha_{1}|1\rangle \longrightarrow X \longrightarrow \alpha_{1}|0\rangle + \alpha_{0}|1\rangle$ $X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \qquad X|0\rangle = |1\rangle$ $X|1\rangle = |0\rangle$ "Hadamard transform"



 $H = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{pmatrix}$

X = HZH

µ² = І н = Н⁻¹

"Phase flip"





- One-qubit gates: $\mathcal{U} = \begin{pmatrix} a & c \\ b & d \end{pmatrix} \qquad \mathcal{U}^{+} = \begin{pmatrix} \overline{a} & \overline{b} \\ \overline{c} & \overline{d} \end{pmatrix}$ $\mathcal{U}^{+} \mathcal{U} = \begin{pmatrix} a & c \\ b & d \end{pmatrix} \begin{pmatrix} a & c \\ b & d \end{pmatrix} \begin{pmatrix} a & c \\ a & c \end{pmatrix} \end{pmatrix} \begin{pmatrix} a & c \\ a & c \end{pmatrix} \begin{pmatrix} a & c \\ a & c \end{pmatrix} \begin{pmatrix} a & c \\ a & c \end{pmatrix} \begin{pmatrix} a & c \\ a & c \end{pmatrix} \end{pmatrix} \begin{pmatrix} a & c \\ a & c \end{pmatrix} \begin{pmatrix} a & c \\ a & c \end{pmatrix} \end{pmatrix} \begin{pmatrix} a & c \\ a & c \end{pmatrix} \end{pmatrix} \begin{pmatrix} a & c \\ a & c \end{pmatrix} \begin{pmatrix} a & c \\ a & c \end{pmatrix} \end{pmatrix} \begin{pmatrix} a & c \\ a & c \end{pmatrix} \end{pmatrix} \begin{pmatrix} a & c \\ a & c \end{pmatrix}$
- What is the dimension of two-qubit gates?

 $\alpha_{00}|00\rangle + \alpha_{01}|01\rangle + \alpha_{10}|10\rangle + \alpha_{11}|11\rangle \qquad \qquad U \qquad \qquad \alpha_{00}'|00\rangle + \alpha_{01}'|01\rangle + \alpha_{10}'|10\rangle + \alpha_{11}'|11\rangle$

$$\mathcal{U} = \begin{pmatrix} a & \vdots & \vdots & \vdots \\ b & \vdots & \vdots & \vdots \\ c & \vdots & \vdots & \vdots \\ d & \vdots & \vdots & \vdots \end{pmatrix} \begin{pmatrix} \alpha'_{00} \\ \alpha'_{01} \\ \alpha'_{10} \\ \alpha'_{11} \end{pmatrix} = U \begin{pmatrix} \alpha_{00} \\ \alpha_{01} \\ \alpha_{10} \\ \alpha_{11} \end{pmatrix}$$
$$\mathcal{U} | 00 \rangle = a | 00 \rangle + b | 01 \rangle + c | 10 \rangle + d | 11 \rangle$$
$$U | 00 \rangle = a | 00 \rangle + b | 01 \rangle + c | 10 \rangle + d | 11 \rangle$$
$$U \text{ is a 4x4 unitary matrix.}$$
$$U U^{\dagger} = U^{\dagger} U = I$$

"CNOT" control
a
a
b
control
a
a
b
$$\oplus a$$

target
a, b $\in \{0, 1\}$
 $CNOT = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 \end{pmatrix}$
 $CNOT = CNOT$
 $CNOT + CNOT = CNOT$
 $CNOT + CNOT = CNOT^{2} = I$

[U2>@ 1 V2> Tensor Producto $|u, \gg |v, >$ inner product トルフ $\langle u_1 | u_2 \rangle \cdot \langle v_1 | v_2 \rangle$ 10) 1 ~~~ 100>+~~ 101>+~ 10 10>+~ 11> Bolo>+ B.11> ~, 10> + d, 11> Ľ² Hi ${\mathfrak S}$ 10>@1v> 12 <u>14</u> $(|u_1\rangle+|u_2\rangle)\otimes|v\rangle = |u_1\rangle\otimes|v\rangle+|u_2\rangle\otimes|v\rangle$ $|u_1\rangle + |u_2\rangle$ 1 ~> $|V_{1}\rangle + |V_{2}\rangle$ 12> 10>310> = 10>10> = 100> 10) 10> 1070 117 = 107117 = 1017 $|\rangle$ 10) 110> (0) 1> (11) 112 こ



 $\begin{aligned}
 \mathcal{U}_{1} &= \begin{pmatrix} q & c \\ 5 & d \end{pmatrix} \\
 \mathcal{U}_{2} &= \begin{pmatrix} q & q \\ -q & h \end{pmatrix}
 \end{aligned}$

 $\mathcal{U} = \mathcal{U}_{1} \otimes \mathcal{U}_{2}$ $\begin{pmatrix} a U_2 & c U_2 \\ b U_2 & dl \end{pmatrix}$